# **Exercise Sheet 11**

discussion on 20.01.2023

## **Exercise 1 (Korn inequality)**

Let  $\Omega \subseteq \mathbb{R}^n$  denote a Lipschitz domain. Recall the definition of the symmetric gradient  $\varepsilon(v) := (D v + D v^{\top})/2$  for all  $v \in H^1(\Omega; \mathbb{R}^n)$ .

(a) Use integration by parts to prove for all  $v \in \mathcal{D}(\Omega; \mathbb{R}^n) \equiv C_c^{\infty}(\Omega; \mathbb{R}^n)$ , that

$$\|\mathbf{D}v\|_{L^2(\Omega)} \lesssim \|\varepsilon(v)\|_{L^2(\Omega)}.$$
(1)

(b) Use a density argument to prove equation (1) for all  $v \in H_0^1(\Omega; \mathbb{R}^n)$ .

### Exercise 2 (Variational formulation of linear elasticity)

Given a right-hand side f and Lamé parameters  $\lambda, \mu > 0$ , the PDEs of linear elasticity with homogeneous Dirichlet boundary conditions seek  $u \in C^2(\Omega; \mathbb{R}^n)$  with

$$-\operatorname{div}(\mathbb{C}\varepsilon(u)) = f \text{ in }\Omega \quad \text{and} \quad u \equiv 0 \text{ on }\partial\Omega, \tag{2}$$

where the material tensor  $\mathbb{C}$  is defined by  $\mathbb{C}M := 2\mu M + \lambda \operatorname{tr}(M) I_{n \times n}$  for  $M \in \mathbb{R}^{n \times n}$ .

- (a) Derive the weak formulation of (2).
- (b) Prove existence and uniqueness of solutions of the variational formulation. *Hint:* Assume that the space H<sup>1</sup><sub>0</sub>(Ω; ℝ<sup>n</sup>) of the deformations *u* is equipped with the usual H<sup>1</sup> energy-norm.

#### Exercise 3 (Conforming P<sub>1</sub> discretization)

Let  $\mathcal{T}$  denote a regular triangulation of the domain  $\Omega$ . Consider the conforming  $P_1$  discretization  $u_h \in S_0^1(\mathcal{T}; \mathbb{R}^n)$  of the deformation  $u \in H_0^1(\Omega; \mathbb{R}^n)$  in the weak formulation of Exercise 2 (a). Use Céa's Lemma to prove a best-approximation result in the  $H^1$  (semi-) norm. How does the generic constant in the estimate depend on the Lamé parameter  $\lambda$  for large  $\lambda$ ?

#### **Exercise 4**

Show that the linear elasticity problem is equivalent to a saddle point problem with a penalty term of the form

$$\begin{aligned} a(u, v) + b(v, p) &= f & \text{für alle } v \in H_0^1(\Omega), \\ b(u, q) + c(p, q) &= 0 & \text{für alle } q \in L^2(\Omega), \end{aligned}$$

where  $p = \lambda \operatorname{div} u$