

(* Koordinatensysteme, WQ, FS 2013 *)

CoordinateTransformData[t, property]

gives the value of the specified property for the coordinate transformation t.

CoordinateTransformData[t, property, {x₁, x₂, ..., x_n}]

gives the value of the property evaluated at the point {x₁, x₂, ..., x_n}.

(* Beispiel Polarkoordinaten 2-dimensional *)

CoordinateTransformData["Cartesian" → "Polar", "Mapping", {x, y}]

CoordinateTransformData["Cartesian" → "Polar", "MappingJacobian", {x, y}]

CoordinateTransformData["Cartesian" → "Polar",

"MappingJacobianDeterminant", {x, y}]

$$\left\{ \sqrt{x^2 + y^2}, \text{ArcTan}[x, y] \right\}$$

$$\left\{ \left\{ \frac{x}{\sqrt{x^2 + y^2}}, \frac{y}{\sqrt{x^2 + y^2}} \right\}, \left\{ -\frac{y}{x^2 + y^2}, \frac{x}{x^2 + y^2} \right\} \right\}$$

$$\frac{1}{\sqrt{x^2 + y^2}}$$

(* In der Ausgabe ist eine 'Kurzform' verwendet:

ArcTan[x, y] gives the arc tangent of y/x,

taking into account which quadrant the point(x, y) is in. *)

(* The mapping function can be requested from

CoordinateTransformData and stored for later use. *)

In[1]:= map = CoordinateTransformData["Cartesian" → "Polar", "Mapping"]

Out[1]= $\left\{ \sqrt{\#1[1]^2 + \#1[2]^2}, \text{ArcTan}[\#1[1], \#1[2]] \right\} \&$

map[{1, 1}]

Out[3]= $\left\{ \sqrt{2}, \frac{\pi}{4} \right\}$

map /@ {{0, 1}, {1, 0}, {1/2, 1/2}, {3, 1/3}}

Out[4]= $\left\{ \left\{ 1, \frac{\pi}{2} \right\}, \{1, 0\}, \left\{ \frac{1}{\sqrt{2}}, \frac{\pi}{4} \right\}, \left\{ \frac{\sqrt{82}}{3}, \text{ArcTan}\left[\frac{1}{9}\right] \right\} \right\}$

```

CoordinateTransformData["Polar" → "Cartesian", "Mapping", {r, θ}]

mp = CoordinateTransformData["Polar" → "Cartesian", "MappingJacobian", {r, θ}]

imp = CoordinateTransformData[
  {"Polar" → "Cartesian", "Euclidean", 2}, "InverseMappingJacobian", {r, θ}]

CoordinateTransformData["Polar" → "Cartesian",
  "MappingJacobianDeterminant", {r, θ}]
{r Cos[θ], r Sin[θ]}

{{Cos[θ], -r Sin[θ]}, {Sin[θ], r Cos[θ]}}
{{Cos[θ], Sin[θ]}, {-Sin[θ]/r, Cos[θ]/r} }

r

mp . imp // Simplify
{{1, 0}, {0, 1} }

(* Anwendung der Transformation von {x,y} zu {r,θ} *)
pt = CoordinateTransform["Cartesian" → "Polar", {x, y}]
{Sqrt[x^2 + y^2], ArcTan[x, y]}

(* Und zurueck *)
CoordinateTransform["Polar" → "Cartesian", pt]
{x, y}

Example : Convert a curve in non - Cartesian coordinates
to a corresponding Cartesian expression for purposes of visualization :

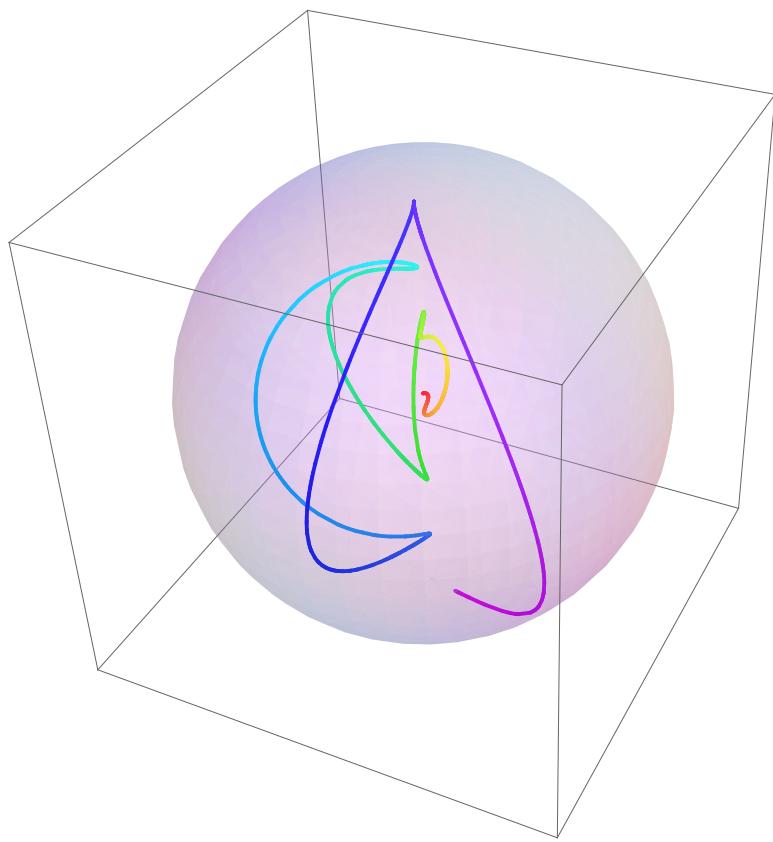
cSpherical[t_] := {t, Pi (1 + Sin[16 t + 4 t^2])/2, 1 + 2 t + 3 t^2}

cCartesian[t_] = CoordinateTransform["Spherical" → "Cartesian", cSpherical[t]]

{t Cos[1 + 2 t + 3 t^2] Sin[Pi (1 + Sin[16 t + 4 t^2])/2],
 t Sin[1 + 2 t + 3 t^2] Sin[Pi (1 + Sin[16 t + 4 t^2])/2], t Cos[Pi (1 + Sin[16 t + 4 t^2])/2]}

```

```
Show[Graphics3D[{Opacity[.25], Sphere[]}], ParametricPlot3D[cCartesian[t],
{t, 0, 1}, PlotStyle -> Thick, ColorFunction -> (Hue[.8 #4] &)]]
```



This curve is approximately 11.2 radii in length :

```
NIntegrate[Sqrt[cCartesian'[t].cCartesian'[t]], {t, 0, 1}]
11.2049

(* in den Sphericals ist es schwieriger, siehe unten: *)
metr = CoordinateChartData[{"Spherical", 3}, "Metric"][[r, \[Theta], \[Phi]]] /.
  {r \[Rule] t, \[Theta] \[Rule] Pi (1 + Sin[16 t + 4 t^2]) / 2}
  {{1, 0, 0}, {0, t^2, 0}, {0, 0, t^2 Sin[\[Pi] (1 + Sin[16 t + 4 t^2]) / 2]^2}}
```

```
NIntegrate[Sqrt[cSpherical'[t].metr.cSpherical'[t]], {t, 0, 1}]
11.2049

(* Koordinaten -- Karten *)
CoordinateChartData["Properties"]

{AlternateCoordinateNames, CoordinateRangeAssumptions,
 Dimension, InverseMetric, Metric, ParameterRangeAssumptions,
 ScaleFactors, StandardCoordinateNames, StandardName, VolumeFactor}
```

```

CoordinateChartData["Polar", "ScaleFactors", {r, θ}]
{1, r}

CoordinateChartData[{"Polar", 2}, "ScaleFactors", {r, θ}]
{1, r}

CoordinateChartData["Polar", "Metric", {r, θ}]
CoordinateChartData["Polar", "InverseMetric", {r, θ}]
{{1, 0}, {0, r^2}}
{{1, 0}, {0, 1/r^2} }

vf = CoordinateChartData["Polar", "VolumeFactor", {r, θ}]
r

$$\int_0^R \int_0^{2\pi} vf \, d\theta \, dr$$


$$\pi R^2$$


CoordinateChartData["Polar", "StandardCoordinateNames", {r, θ}]
{r, θ}

% // InputForm
{"r", "θ"}

ToExpression @% // InputForm
{r, θ}

test = CoordinateChartData[{"Polar", 2}, "CoordinateRangeAssumptions"]
#1[[1]] > 0 && -π < #1[[2]] ≤ π &

test[{3, π/2}] (* gueltiger Punkt *)
True

test[{-3, π/2}] (* ungueltiger Punkt *)
False

(* Verwendung der Metrik, Beispiel Zylinder-Koordinaten,
die auf einer Helix verwendet werden koennen.
Give the components of the (covariant) metric as a matrix: *)

CoordinateChartData[{"Cylindrical", 3}, "Metric"][{r, θ, z}]
{{1, 0, 0}, {0, r^2, 0}, {0, 0, 1}}

(* By particularizing to a curve,
the metric can be used to compute the differential arc length *)

metric[t_] = CoordinateChartData[{"Cylindrical", 3}, "Metric"][{r[t], θ[t], z[t]}]
{{1, 0, 0}, {0, r[t]^2, 0}, {0, 0, 1}}

```

```

helix[t_] = {a, b t, c t}

helix'[t] . metric[t].helix'[t] /. r[t] → a
{a, b t, c t}
a2 b2 + c2

(* Allgemeine Anwendung:
A function to compute the differential arc
length of a curve in a particular coordinate system: *)
ds[curve_List, t_, chart_] := Module[{metric, tangent},
  metric = CoordinateChartData[chart, "Metric", curve];
  tangent = D[curve, t];
  Sqrt[tangent . metric . tangent] dt
]
(* The differential arc length of a general curve in polar coordinates: *)

ds[{r[t], θ[t]}, t, "Polar"]
dt √r'[t]2 + r[t]2 θ'[t]2

(* The differential arc length of a
helix expressed in cylindrical coordinates: *)
ds[{R, u, u}, u, {"Cylindrical", 3}]
√1 + R2 du

(* This can now be integrated: *)
s[t_] := Integrate[√1 + R2, u]
s[t] (* Die wahre Bogenlaenge ist somit *)
√1 + R2 t

(* Analoge 3-dimensionale Transformation *)

CoordinateTransformData["Cartesian" → "Spherical", "Mapping", {x, y, z}]
{√x2 + y2 + z2, ArcTan[z, √x2 + y2], ArcTan[x, y]}

CoordinateTransformData["Spherical" → "Cartesian", "Mapping", {r, θ, φ}]
{r Cos[φ] Sin[θ], r Sin[θ] Sin[φ], r Cos[θ]}

```

```

CoordinateTransformData["Spherical" → "Cartesian", "Mapping", {r, θ, φ}]
CoordinateTransformData["Cartesian" → "Polar", "MappingJacobian", {x, y}]
CoordinateTransformData["Spherical" → "Cartesian", "Mapping", {r, θ, φ}]
{r Cos[φ] Sin[θ], r Sin[θ] Sin[φ], r Cos[θ]}

{ {x / Sqrt[x^2 + y^2], y / Sqrt[x^2 + y^2]}, {-y / (x^2 + y^2), x / (x^2 + y^2)} }

{r Cos[φ] Sin[θ], r Sin[θ] Sin[φ], r Cos[θ]}

vf = CoordinateChartData[{"Spherical", 3}, "VolumeFactor", {r, θ, φ}]
r^2 Sin[θ]


$$\int_0^R \int_0^\pi \int_0^{2\pi} vf \, dr \, d\theta \, d\varphi$$


$$\frac{4 \pi R^3}{3}$$


(* Allgemeine Uebersicht zu Koordinatensystemen in der Ebene *)
CoordinateChartData[{All, 2}]
{{{Bipolar, {a}}, Euclidean, 2}, {Cartesian, Euclidean, 2},
 {{Confocal, {a, b}}, Euclidean, 2}, {{Elliptic, {a}}, Euclidean, 2},
 {Polar, Euclidean, 2}, {PlanarParabolic, Euclidean, 2} }

(* Allgemeine Uebersicht zu Koordinatensystemen im 3-
dimensionalen Euklidischen Raum *)
CoordinateChartData[{All, 3}]
{{{BipolarCylindrical, {a}}, Euclidean, 3},
 {{Bispherical, {a}}, Euclidean, 3}, {Cartesian, Euclidean, 3},
 {CircularParabolic, Euclidean, 3}, {{Confocal, {a, b, c}}, Euclidean, 3},
 {{ConfocalParaboloidal, {a, b}}, Euclidean, 3}, {{Conical, {b, c}}, Euclidean, 3},
 {Cylindrical, Euclidean, 3}, {{EllipticCylindrical, {a}}, Euclidean, 3},
 {Hyperspherical, Euclidean, 3}, {{OblateSpheroidal, {a}}, Euclidean, 3},
 {ParabolicCylindrical, Euclidean, 3}, {{ProlateSpheroidal, {a}}, Euclidean, 3},
 {Spherical, Euclidean, 3}, {{Toroidal, {a}}, Euclidean, 3} }

(* Ein gegebenes Vektorfeld in andere Koordinaten umrechnen *)
TransformedField[t, f, {x1, x2, ..., xn} → {y1, y2, ..., yn}]
(*
uses the coordinate transformation t to transform the scalar,
vector, or tensor field f from coordinates xi to yi. *)

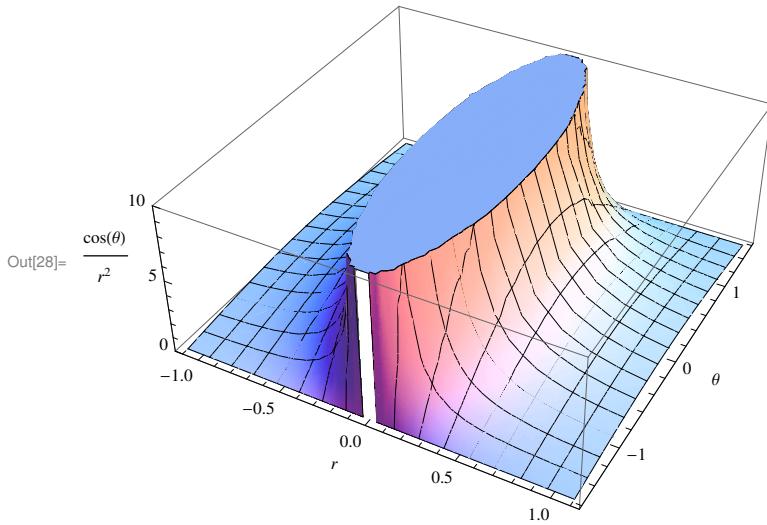
```

(* Beispiel: An electric dipole of dipole moment p located at the origin and aligned with the z axis has the following electric potential in spherical coordinates:

In[23]:= $V_s = (p \cos[\theta]) / r^2$

$$\text{Out[23]}= \frac{p \cos[\theta]}{r^2}$$

In[28]:= $\text{Plot3D}\left[\frac{\cos[\theta]}{r^2}, \{r, -1.1, 1.1\}, \{\theta, -\pi/2, \pi/2\}, \text{PlotRange} \rightarrow \{0, 10\}, \text{AxesLabel} \rightarrow \{r, \theta, V_s / . p \rightarrow 1\}\right]$



Compute the corresponding expression in Cartesian coordinates :

In[24]:= $V_c = \text{TransformedField["Spherical" \rightarrow "Cartesian"], } V_s, \{r, \theta, \varphi\} \rightarrow \{x, y, z\}]$

$$\text{Out[24]}= \frac{p z}{(x^2 + y^2 + z^2)^{3/2}}$$

Derive the dipole electric field in spherical coordinates :

!! Der Gradient kann einfach als Grad angesetzt werden,
wenn man noch das verwendete Koordinatensystem angibt !!

In[25]:= $E_s = -\text{Grad}[V_s, \{r, \theta, \varphi\}, \text{"Spherical"}]$

$$\text{Out[25]}= \left\{ \frac{2 p \cos[\theta]}{r^3}, \frac{p \sin[\theta]}{r^3}, 0 \right\}$$

Transform this expression to Cartesian coordinates :

In[26]:= $E_c = \text{TransformedField["Spherical" \rightarrow "Cartesian"], } E_s, \{r, \theta, \varphi\} \rightarrow \{x, y, z\}]$

$$\text{Out[26]}= \left\{ \frac{3 p x z}{(x^2 + y^2 + z^2)^{5/2}}, \frac{3 p y z}{(x^2 + y^2 + z^2)^{5/2}}, -\frac{p (x^2 + y^2)}{(x^2 + y^2 + z^2)^{5/2}} + \frac{2 p z^2}{(x^2 + y^2 + z^2)^{5/2}} \right\}$$

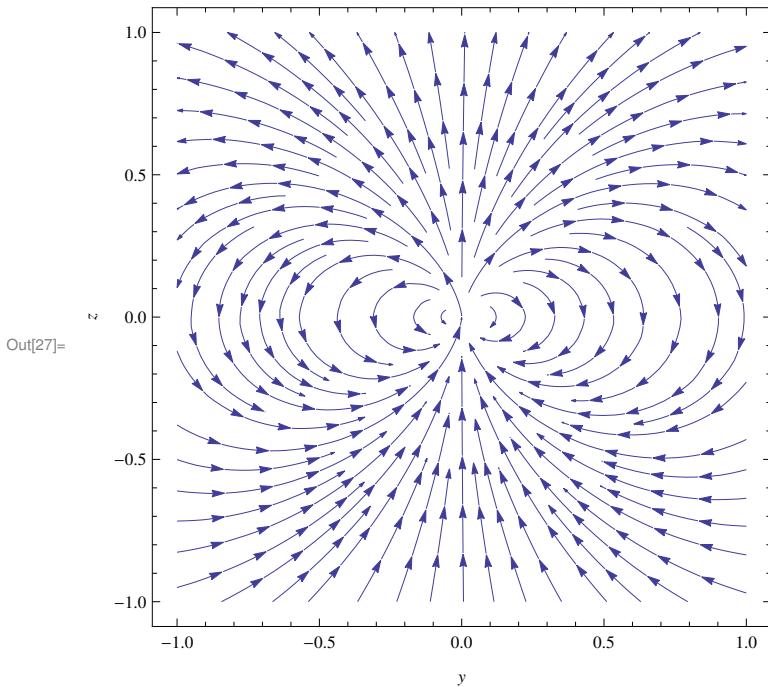
The same expression is obtained by differentiating the Cartesian potential function :

$E_c == -\text{Grad}[V_c, \{x, y, z\}] // \text{Simplify}$

True

Plot the lines of force in the yz plane :

```
In[27]:= StreamPlot[Rest[Ec /. {p → 1, x → 0}] // Evaluate,
{y, -1, 1}, {z, -1, 1}, FrameLabel → {y, z}]
```



```
(* Rest verwendet die erste Komponente nicht;
damit sind wir fuer Ec wirklich in der yz - Ebene *)
```

```
(* This transforms a rank-2 tensor
from Cartesian to polar coordinates. *)
```

```
mat = {{x^2 + y^2, 0}, {0, x^2 y^2}}
```

```
Out[5]= {x^2 + y^2, 0}, {0, x^2 y^2}
```

```
TransformedField["Cartesian" → "Polar", mat, {x, y} → {r, θ}] // Simplify
```

```
Out[19]= {r^2 Cos[θ]^2 (Cos[θ]^2 + Sin[θ]^2 + r^2 Sin[θ]^4), -1/16 r^2 (8 - r^2 + r^2 Cos[4 θ]) Sin[2 θ]}, {-1/16 r^2 (8 - r^2 + r^2 Cos[4 θ]) Sin[2 θ], r^2 Sin[θ]^2 (Cos[θ]^2 + r^2 Cos[θ]^4 + Sin[θ]^2)}
```

```
(* man beachte, dass dies keine Diagonalmatrix mehr ist ! *)
```

Using Map,
it is possible to transform the matrix as a
list of two vectors or as a matrix of four scalar fields.
The results are quite different in each case.

```
In[17]:= Map[TransformedField["Cartesian" → "Polar", #, {x, y} → {r, θ}] &, mat] // Expand
TrigReduce[%]

Out[17]= {r^2 Cos[θ]^3 + r^2 Cos[θ] Sin[θ]^2, -r^2 Cos[θ]^2 Sin[θ] - r^2 Sin[θ]^3},
{r^4 Cos[θ]^2 Sin[θ]^3, r^4 Cos[θ]^3 Sin[θ]^2}

Out[18]= { {r^2 Cos[θ], -r^2 Sin[θ]}, {1/16 (2 r^4 Sin[θ] + r^4 Sin[3 θ] - r^4 Sin[5 θ]), 1/16 (2 r^4 Cos[θ] - r^4 Cos[3 θ] - r^4 Cos[5 θ])} }

(* hier versagt bei der Vereinfachung auch TrigReduce:
-r^2 Cos[θ]^2 Sin[θ]-r^2 Sin[θ]^3 = -r^2 Sin[θ]
r^4 Cos[θ]^2 Sin[θ]^3 = r^4 Sin[θ] 1/8 (1-Cos[4 θ])
r^4 Cos[θ]^3 Sin[θ]^2 = r^4 Cos[θ] 1/8 (1-Cos[4 θ])
mit *)
TrigReduce[Cos[θ]^2 Sin[θ]^2]

Out[21]= 1/8 (1 - Cos[4 θ])

In[13]:= Map[TransformedField["Cartesian" → "Polar", #, {x, y} → {r, θ}] &, mat, {2}] // Simplify

Out[13]= { {r^2, 0}, {0, r^4 Cos[θ]^2 Sin[θ]^2} }

(* Dies bekommt man also, wenn man direkt komponentenweise in mat die
Koordinatentransformation einsetzt. *)
```