

Zum Mma - Kurs, Dr. W. Quapp, FS 2013
Ableitungen und Differentialgleichungen

Defining Derivatives --- from Mma Help System ---

You can define the derivative in *Mathematica* of a function f of one argument simply by an assignment like $f'[x_] = fp[x]$.

This defines the derivative of $f(x)$ to be $fp(x)$. In this case, you could have used $=$ instead of $:=$.

```
f'[x_] := fp[x]
```

The rule for $f'[x_]$ is used to evaluate this derivative.

```
D[f[x^2], x]
```

```
2 x fp[x^2]
```

Differentiating again gives derivatives of fp .

```
D[%, x]
```

```
2 fp[x^2] + 4 x^2 fp'[x^2]
```

This defines a value for the derivative of g at the origin.

```
g'[0] = g0
```

```
g0
```

The value for $g'[0]$ is used.

```
D[g[x]^2, x] /. x -> 0
```

```
2 g0 g[0]
```

This defines the second derivative of g , with any argument.

```
g''[x_] = gpp[x]
```

```
gpp[x]
```

The value defined for the second derivative is used.

```
D[g[x]^2, {x, 2}]
```

```
2 g[x] gpp[x] + 2 g'[x]^2
```

DSolve --- Aufgaben aus Mma Hilfe

```
DSolve[y'[x] + y[x] == a Sin[x], y[x], x]
```

```
{ { y[x] -> e^{-x} C[1] + \frac{1}{2} a (-Cos[x] + Sin[x]) } }
```

Include a boundary condition :

`DSolve[{y'[x] + y[x] == a Sin[x], y[0] == 0}, y[x], x]`

$\left\{ \left\{ y[x] \rightarrow -\frac{1}{2} a e^{-x} (-1 + e^x \cos[x] - e^x \sin[x]) \right\} \right\}$

Get a "pure function" solution for y :

`DSolve[{y'[x] + y[x] == a Sin[x], y[0] == 0}, y, x]`

$\left\{ \left\{ y \rightarrow \text{Function}\left[\{x\}, -\frac{1}{2} a e^{-x} (-1 + e^x \cos[x] - e^x \sin[x]) \right] \right\} \right\}$

Substitute the solution into any expression :

`FullSimplify[y''[x] + y[x]^2 /. %]`

$\left\{ \frac{1}{4} a e^{-2x} \left(a - 2 e^x (-1 + a \cos[x] - a \sin[x]) + e^{2x} (a + 2 \cos[x] - 2 \sin[x] - a \sin[2x]) \right) \right\}$

Diff. equ. of second order : no boundary condition gives two generated parameters :

`DSolve[y''[x] + 4 y[x] == 0, y, x]`

$\{ \{ y \rightarrow \text{Function}\left[\{x\}, C[1] \cos[2x] + C[2] \sin[2x] \right] \} \}$

One boundary condition :

`DSolve[{y''[x] + 4 y[x] == 0, y[0] == 1}, y, x]`

$\{ \{ y \rightarrow \text{Function}\left[\{x\}, \cos[2x] + C[2] \sin[2x] \right] \} \}$

Two boundary conditions (one value of the function, one of the derivative)

`DSolve[{y''[x] + 4 y[x] == 0, y[0] == 1, y'[0] == 4}, y, x]`

$\{ \{ y \rightarrow \text{Function}\left[\{x\}, \cos[2x] + 2 \sin[2x] \right] \} \}$

or (two values of the function)

`DSolve[{y''[x] + 4 y[x] == 0, y[0] == 1, y[1] == 2}, y, x]`

$\{ \{ y \rightarrow \text{Function}\left[\{x\}, \cos[2x] - \cot[2] \sin[2x] + 2 \csc[2] \sin[2x] \right] \} \}$

Use differently named constants :

`DSolve[y''[x] == y[x], y[x], x, GeneratedParameters -> d]`

$\{ \{ y[x] \rightarrow e^x d[1] + e^{-x} d[2] \} \}$

Use subscripted constants :

`DSolve[y''[x] == y[x], y[x], x, GeneratedParameters -> (Subscript[c, #] &)]`

$\{ \{ y[x] \rightarrow e^x c_1 + e^{-x} c_2 \} \}$

Solve a logistic equation :

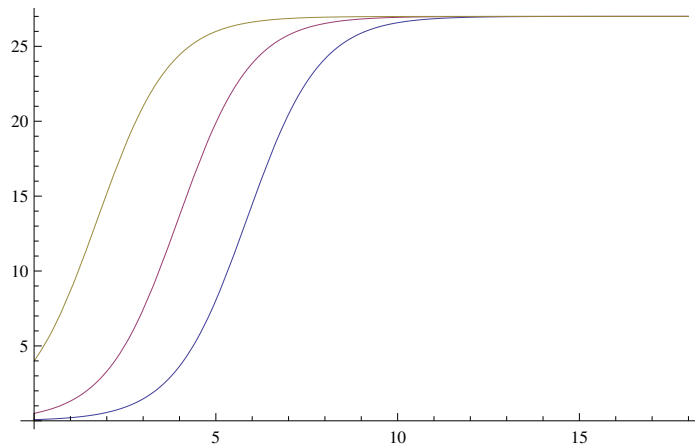
```
DSolve[{y'[x] == y[x] (1 - y[x] / 27), y[0] == a}, y, x]
```

Solve::ifun : Inverse functions are being used by Solve, so some solutions may not be found; use Reduce for complete solution information. >>

```
{ {y -> Function[{x},  $\frac{27 a e^x}{27 - a + a e^x}$ ] ] }
```

Plot the solution for different initial values :

```
Plot[Evaluate[y[x] /. % /. {{a -> 1 / 13}, {a -> 1 / 2}, {a -> 4}}, {x, 0, 18}]
```

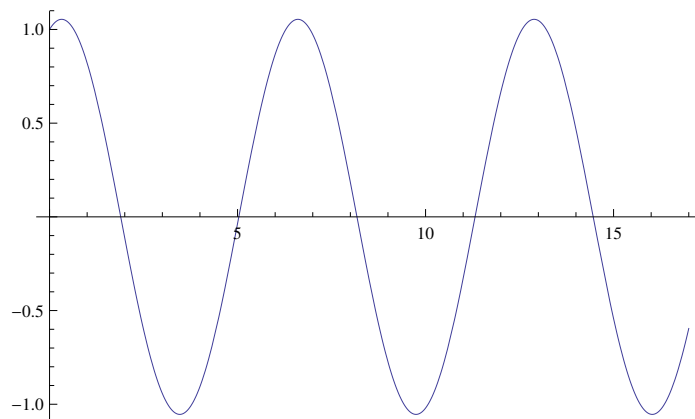


Solve a linear pendulum equation :

```
DSolve[{y''[x] + y[x] == 0, y[0] == 1, y'[0] == 1 / 3}, y, x]
```

```
{ {y -> Function[{x},  $\frac{1}{3} (3 \text{Cos}[x] + \text{Sin}[x])$ ] ] }
```

```
Plot[y[x] /. %, {x, 0, 17}]
```

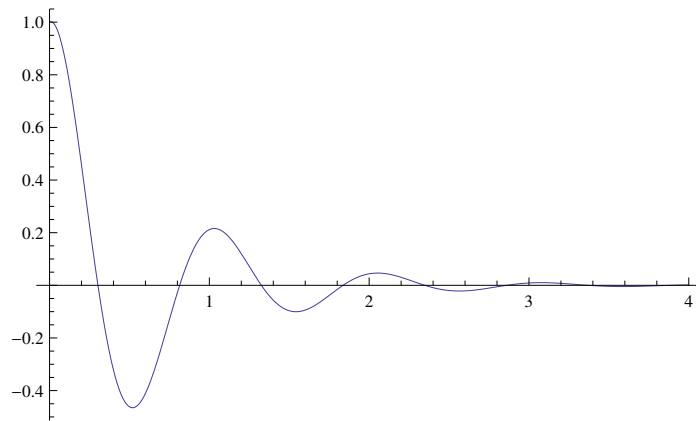


Displacement of a linear, damped pendulum :

```
DSolve[{y''[x] + 3 y'[x] + 40 y[x] == 0, y[0] == 1, y'[0] == 1 / 3}, y, x]
```

```
{ {y -> Function[{x},  $\frac{1}{453} e^{-3x/2} \left( 453 \text{Cos}\left[\frac{\sqrt{151} x}{2}\right] + 11 \sqrt{151} \text{Sin}\left[\frac{\sqrt{151} x}{2}\right] \right)$ ] ] }
```

```
Plot[y[x] /. %, {x, 0, 4}, PlotRange -> All]
```



Find a power series solution when the exact solution is known :

```
DSolve[{y'[x] + Exp[x] y[x] == 1, y[0] == 3}, y, x]
```

```
{{y -> Function[{x}, e-ex (3 e - ExpIntegralEi[1] + ExpIntegralEi[ex]) ]}}
```

```
Series[y[x] /. %[[1]], {x, 0, 7}]
```

$$3 - 2x - \frac{x^2}{2} + \frac{x^3}{3} + \frac{x^4}{6} - \frac{x^5}{120} - \frac{11x^6}{360} - \frac{x^7}{105} + O[x]^8$$

Recover a function from its gradient vector :

```
DSolve[{D[f[x, y], x] == 2 x y^3 + y Cos[x y],
```

```
        D[f[x, y], y] == 3 x^2 y^2 + x Cos[x y]}, f[x, y], {x, y}]
```

```
{{f[x, y] -> x^2 y^3 + C[1] + Sin[x y]}}
```

Solutions satisfy the differential equation and boundary conditions :

```
DSolve[{y'[x] - y[x] == 0, y[0] == 1, y'[0] == 4}, y, x]
```

```
{{y -> Function[{x}, \frac{1}{2} e^{-x} (-3 + 5 e^{2x}) ]}}
```

```
Simplify[{y'[x] - y[x] == 0, y[0] == 1, y'[0] == 4} /. %]
```

```
{{True, True, True}}
```

Differential equation corresponding to Integrate

```
DSolve[y'[x] == Exp[-x^2], y, x]
```

```
{{y -> Function[{x}, C[1] + \frac{1}{2} \sqrt{\pi} Erf[x] ]}}
```

```
Integrate[Exp[-x^2], x]
```

$$\frac{1}{2} \sqrt{\pi} \operatorname{Erf}[x]$$

Use NDSolve to find a numerical solution :

```
exactsol = DSolve[{y''[x] + y[x] == 0, y[0] == 1, y'[0] == 0}, y, x]
{{y -> Function[{x}, Cos[x]]}}
```

```
Table[y[x] /. exactsol[[1]], {x, -2., 2}]
```

```
numsol = NDSolve[{y''[x] + y[x] == 0, y[0] == 1, y'[0] == 0}, y, {x, -2, 2}]
{{y -> InterpolatingFunction[{{-2., 2.}}, <>]}}
```

```
Table[y[x] /. numsol[[1]], {x, -2., 2}]
{-0.416147, 0.540302, 1., 0.540302, -0.416147}
```

Compute an impulse response

```
DSolve[y''''[x] - 5 y'''[x] + 9 y''[x] - 5 y'[x] ==
  DiracDelta''[x] + 2 DiracDelta'[x] + DiracDelta[x] &&
  y[-1] == 0 && y'[-1] == 0 && y''[-1] == 0, y[x], x] // FullSimplify
{{y[x] -> -e^x HeavisideTheta[x] (-2 + e^x (Cos[x] - 7 Sin[x]))}}
```

The same computation using InverseLaplaceTransform

```
InverseLaplaceTransform[ $\frac{s^2 + 2s + 1}{s^3 - 5s^2 + 9s - 5}$ , s, x] // FullSimplify
e^x (2 - e^x (Cos[x] - 7 Sin[x]))
```

Results may contain symbolic integrals :

```
DSolve[y'[x] == f[x], y, x]
{{y -> Function[{x}, C[1] +  $\int_1^x f[K[1]] dK[1]$ ]}}
```

Inverse functions may be required to find the solution :

```
DSolve[{y'[x]^2 == (1 - y[x]^2) (1 - (1/2) y[x]^2), y[0] == 0}, y, x]
```

Solve::ifun : Inverse functions are being used by Solve, so some solutions may not be found; use Reduce for complete solution information. >>

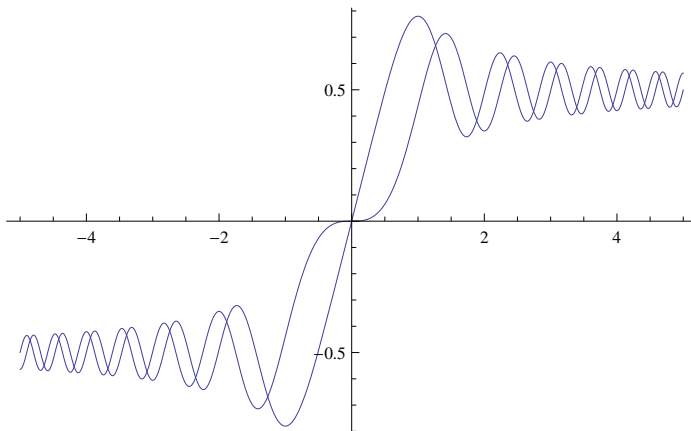
```
{{y -> Function[{x}, -JacobiSN[x,  $\frac{1}{2}$ ] ]}, {y -> Function[{x}, JacobiSN[x,  $\frac{1}{2}$ ] ]}}
```

Generate a Cornu spiral :

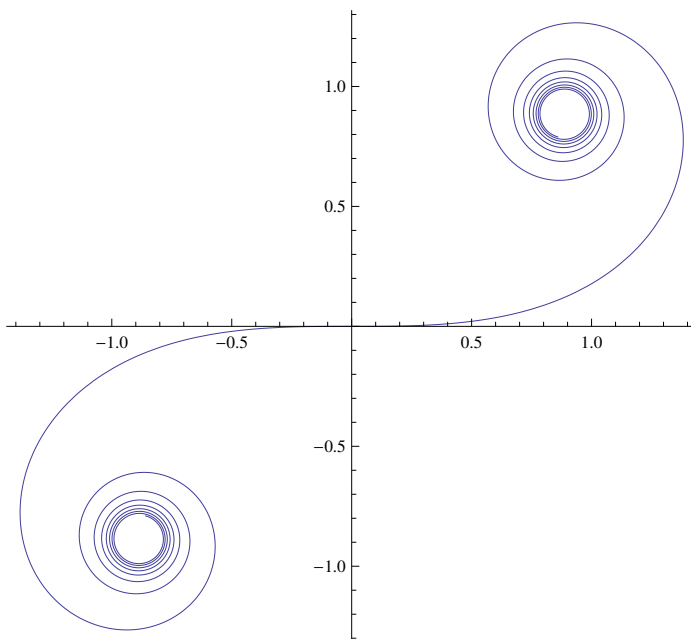
```
DSolve[{x'[s] == Cos[t[s]], y'[s] == Sin[t[s]],
  t'[s] == s, x[0] == 0, y[0] == 0, t[0] == 0}, {x, y, t}, s]
{{t -> Function[{s},  $\frac{s^2}{2}$ ], x -> Function[{s},  $\sqrt{\pi}$  FresnelC[ $\frac{s}{\sqrt{\pi}}$ ]],
  y -> Function[{s},  $\sqrt{\pi}$  FresnelS[ $\frac{s}{\sqrt{\pi}}$ ]]}}
```

Die Loesung enthaelt die Fresnel Funktionen

```
fc = Plot[FresnelC[x], {x, -5, 5}];
fs = Plot[FresnelS[x], {x, -5, 5}];
Show[fc, fs]
```



```
ParametricPlot[Evaluate[{x[s], y[s]} /. %], {s, -10, 10}]
```



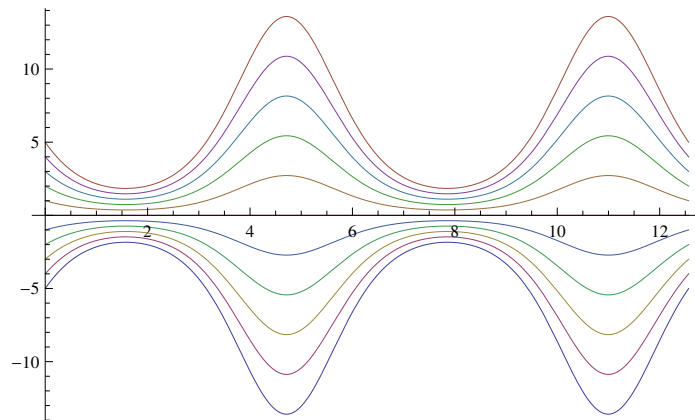
(* ##### *)

(* Weitere Beispiele: DGl mit gewoehnlicher Funktionsdefinition *)

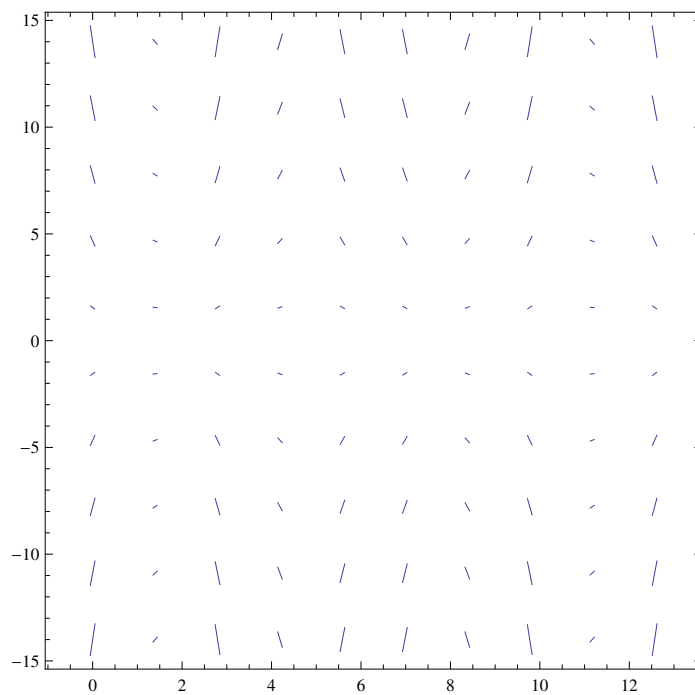
```
lsg = DSolve[y'[x] == -Cos[x] * y[x], y[x], x]
{{y[x] -> e-Sin[x] C[1]}}
```

```
(* Versionen der Behandlung der Ausgabe *)
lsg[[1]]
lsg[[1, 1]]
lsg[[1, 1, 2]]
{y[x] → e-Sin[x] C[1]}
y[x] → e-Sin[x] C[1]
e-Sin[x] C[1]

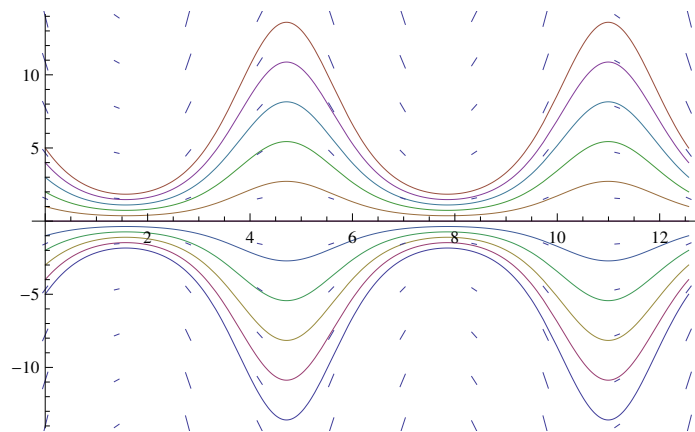
zumbild = Table[lsg[[1, 1, 2]] /. C[1] → j, {j, -5, 5}];
p1 = Plot[Evaluate[zumbild], {x, 0, 4 Pi}]
```



```
(* Veranschaulichung des Vektorfeldes der Differentialgleichung *)
p2 = VectorPlot[{1, -Cos[x] * y}, {x, 0, 4 Pi}, {y, -14, 14},
  VectorPoints → 10, VectorScale → {0.05}, VectorStyle → Arrowheads[0]]
```

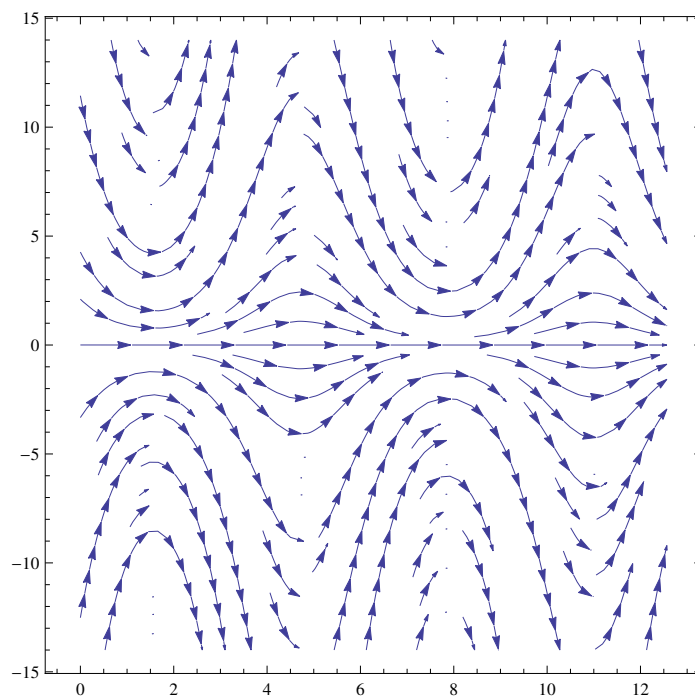


Show[p1, p2]



Bilder in einem Mma - Befehl kombiniert :

```
StreamPlot[{1, -Cos[x] * y}, {x, 0, 4 Pi}, {y, -14, 14}]
```



Welche Darstellung "besser" ist,
haengt sicher auch vom persoenlichen Geschmack ab

(* Es geht nicht: deshalb besser mit "pure function" arbeiten *)

```
y'[x] /. lsg
```

```
{y'[x]}
```

```
lsg2 = DSolve[y'[x] == -Cos[x] * y[x], y, x]
```

```
{{y -> Function[{x}, e^{-Sin[x]} C[1]]}}
```

```
y'[x] /. lsg2
```

```
{-e^{-Sin[x]} C[1] Cos[x]}
```


(* z.B. beliebige Werte einsetzen *)

```
y[t-2] /. lsg2
```

```
{eSin[2-t] C[1]}
```

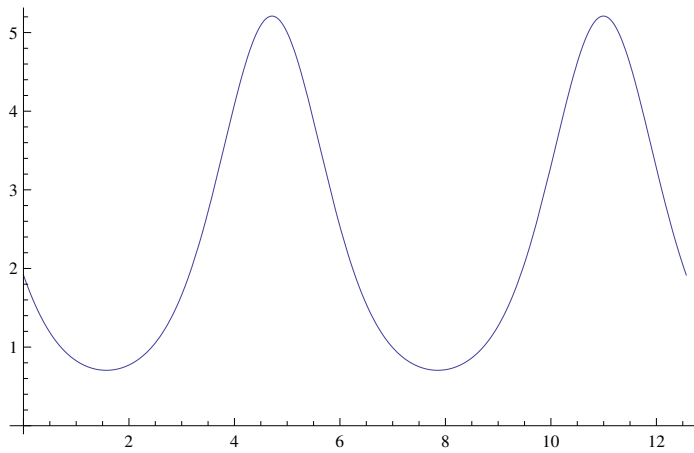
Da volle Familie von Kurven die Ebene ueberdeckt,
kann jeder AW kann getroffen werden z.B.

(* Hinweis zur Fehlerbehandlung = >> Unset[y[5]] *)

```
lsg3 = DSolve[{y'[x] == -Cos[x] * y[x], y[5] == 5}, y, x]
```

```
{{y -> Function[{x}, 5 eSin[5]-Sin[x]]}}
```

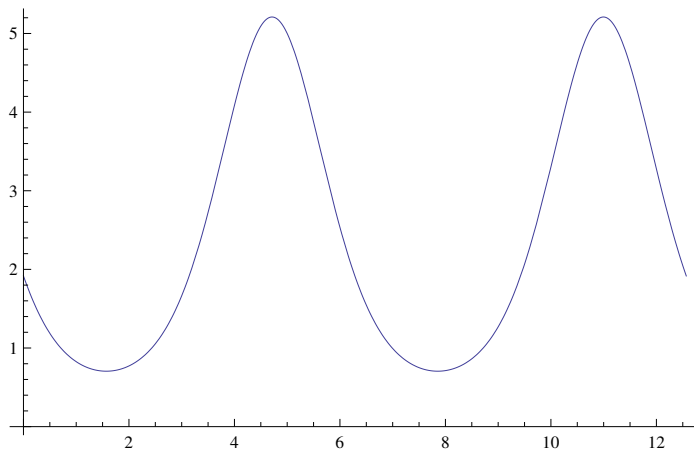
```
Plot[y[x] /. lsg3, {x, 0, 4 Pi}]
```



Plot geht mit den {{ }} weil es automatisch Flatten anwendet .

Ohne AW in der DGl kann man auch eine entsprechende Kurve einzeln malen ,
wenn man C[1] richtig schaeztzt ... ,
oder wieder eine liste von Werteb einsetzen

```
Plot[y[x] /. lsg2 /. c[1] -> 2, {x, 0, 4 Pi}]
```



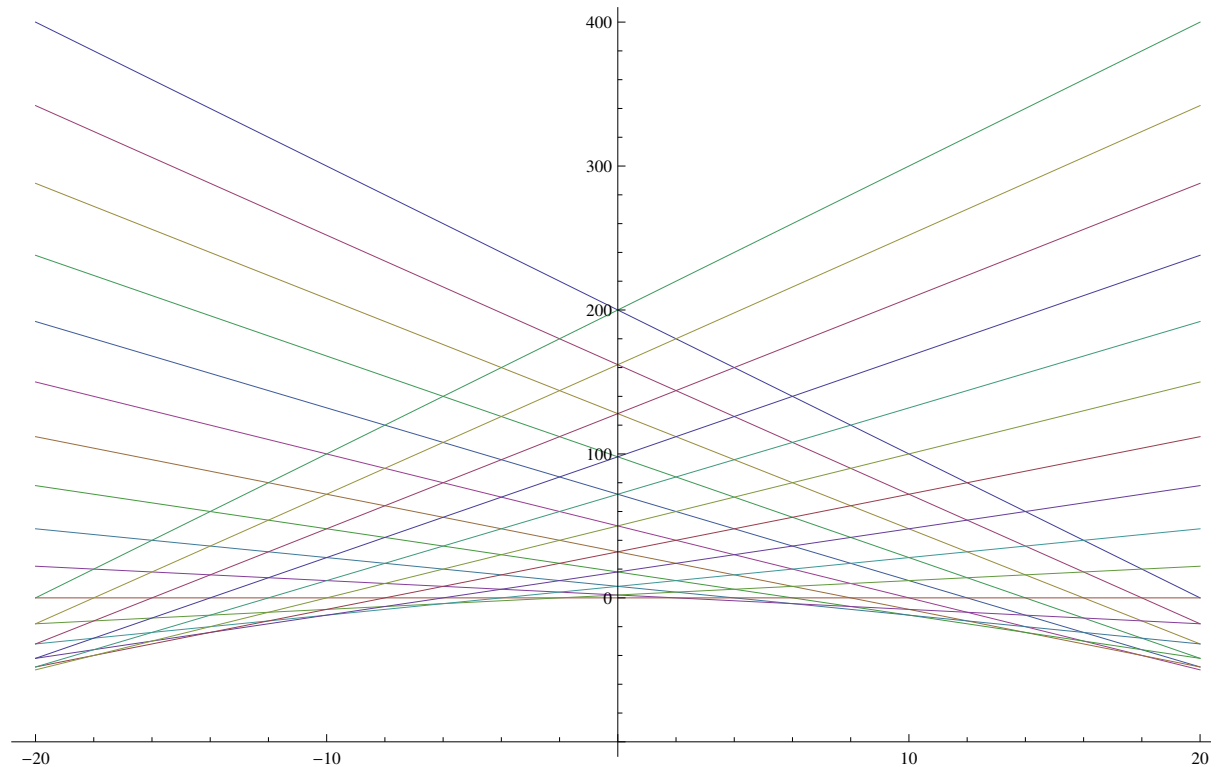
(* BSP: Mma findet Einhuellende bei einer nichtlinearen DGl nicht *)

```
eqn = y'[x]^2 + 1/2 * x * y'[x] - y[x] / 2 == 0;
```

```

lsg4 = DSolve[eqn, y, x]
{{y -> Function[{x}, x C[1] + 2 C[1]^2]}}
druck = Table[y[x] /. lsg4 /. C[1] -> j, {j, -10, 10}];
Plot[druck, {x, -20, 20}, AxesOrigin -> {0, -100}]

```



Hier raten, dass die Enveloppe eine Parabel

fist (First[expr] gives the first element in expr,
siehe auch: Part, Last, Rest, Take, Select)

```

f = a2 x^2 + a1 x + a0;
sys = First[eqn] /. {y[x] -> f, y'[x] -> D[f, x]}
1/2 x (a1 + 2 a2 x) + (a1 + 2 a2 x)^2 + 1/2 (-a0 - a1 x - a2 x^2)

```

```
sol = Solve[CoefficientList[sys, x] == 0 && a2 != 0]
```

```
{{{a0 -> 0, a2 -> -1/8, a1 -> 0}}}
```

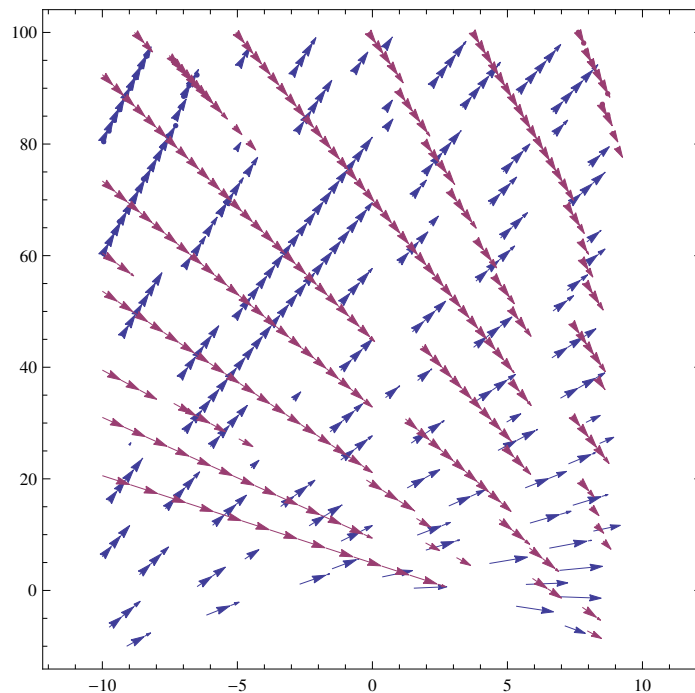
Diese spezielle Loesung ist also $y[x] =$

```
f /. sol
```

```
{-x^2/8}
```

StreamPlot ist hier etwas ueberfordert,
obwohl man die Loesungen auch sehen kann, wenn man sie schon kennt :

```
StreamPlot[{{1, 1/4 (-x + Sqrt[x^2 + 8 y])}, {1, 1/4 (-x - Sqrt[x^2 + 8 y])}}, {x, -10, 10}, {y, -10, 100}]
```



Das Auflösen der DGL "mit Hand" bringt auch keine bessere Einsicht, und auch keine Enveloppe :

```
lsgauf = DSolve[y' [x] == 1/4 (-x - Sqrt[x^2 + 8 y[x]]), y, x]
```

$$\left\{ \left\{ y \rightarrow \text{Function} \left[\{x\}, \frac{1}{64} \left(8 + e^{2c[1]} + 16x - 4\sqrt{2} \sqrt{e^{2c[1]} + 2e^{2c[1]}x + e^{2c[1]}x^2} \right) \right] \right\}, \right. \\ \left. \left\{ y \rightarrow \text{Function} \left[\{x\}, \frac{1}{64} \left(8 + e^{2c[1]} + 16x + 4\sqrt{2} \sqrt{e^{2c[1]} + 2e^{2c[1]}x + e^{2c[1]}x^2} \right) \right] \right\} \right\}$$

```
lsgaufaw = DSolve[{y' [x] == 1/4 (-x + Sqrt[x^2 + 8 y[x]]), y[0] == 100}, y, x]
```

Solve::ifun : Inverse functions are being used by Solve, so some solutions may not be found; use Reduce for complete solution information. >>

$$\left\{ \left\{ y \rightarrow \text{Function} \left[\{x\}, \frac{1}{4} \left(401 + 20\sqrt{2} + x - \sqrt{801 + 40\sqrt{2}} \sqrt{(1+x)^2} \right) \right] \right\}, \right. \\ \left. \left\{ y \rightarrow \text{Function} \left[\{x\}, \frac{1}{4} \left(401 - 20\sqrt{2} + x + \sqrt{-(-801 + 40\sqrt{2}) (1+x)^2} \right) \right] \right\} \right\}$$

(* Bsp: System von 2 Gleichungen: Konkurrierende Spezies, vergleiche die logistische Gleichung fuer eine Dimension *)

```
f[x_, y_] := x (a - b1 x - b2 y)
```

```
g[x_, y_] := y (c - d1 x - d2 y)
```

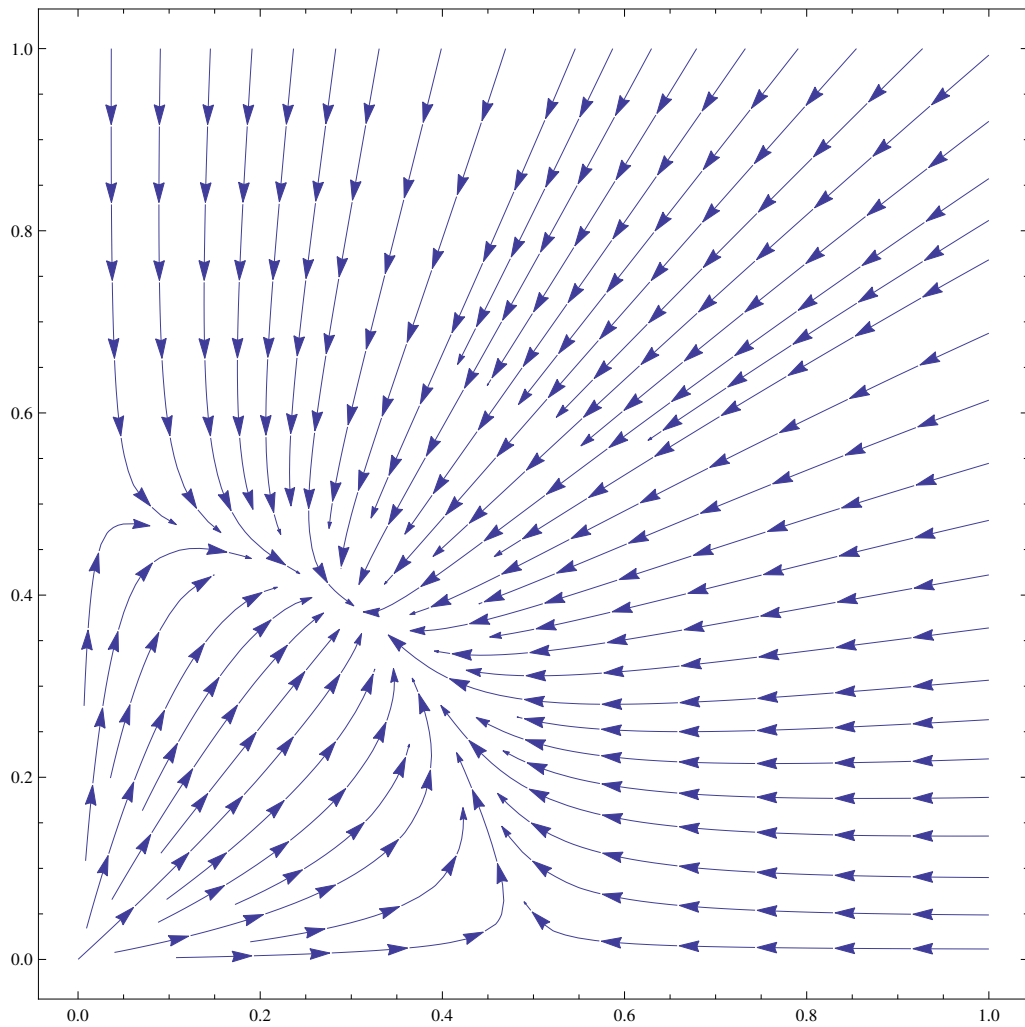
(* Bsp Belegung der Parameter *)

```
a = 1; b1 = 2; b2 = 1; c = 1; d1 = 0.75; d2 = 2;
```

```
sys = {f[x, y], g[x, y]}
```

```
{x (1 - 2 x - y), (1 - 0.75 x - 2 y) y}
```

```
StreamPlot[sys, {x, 0, 1}, {y, 0, 1}]
```

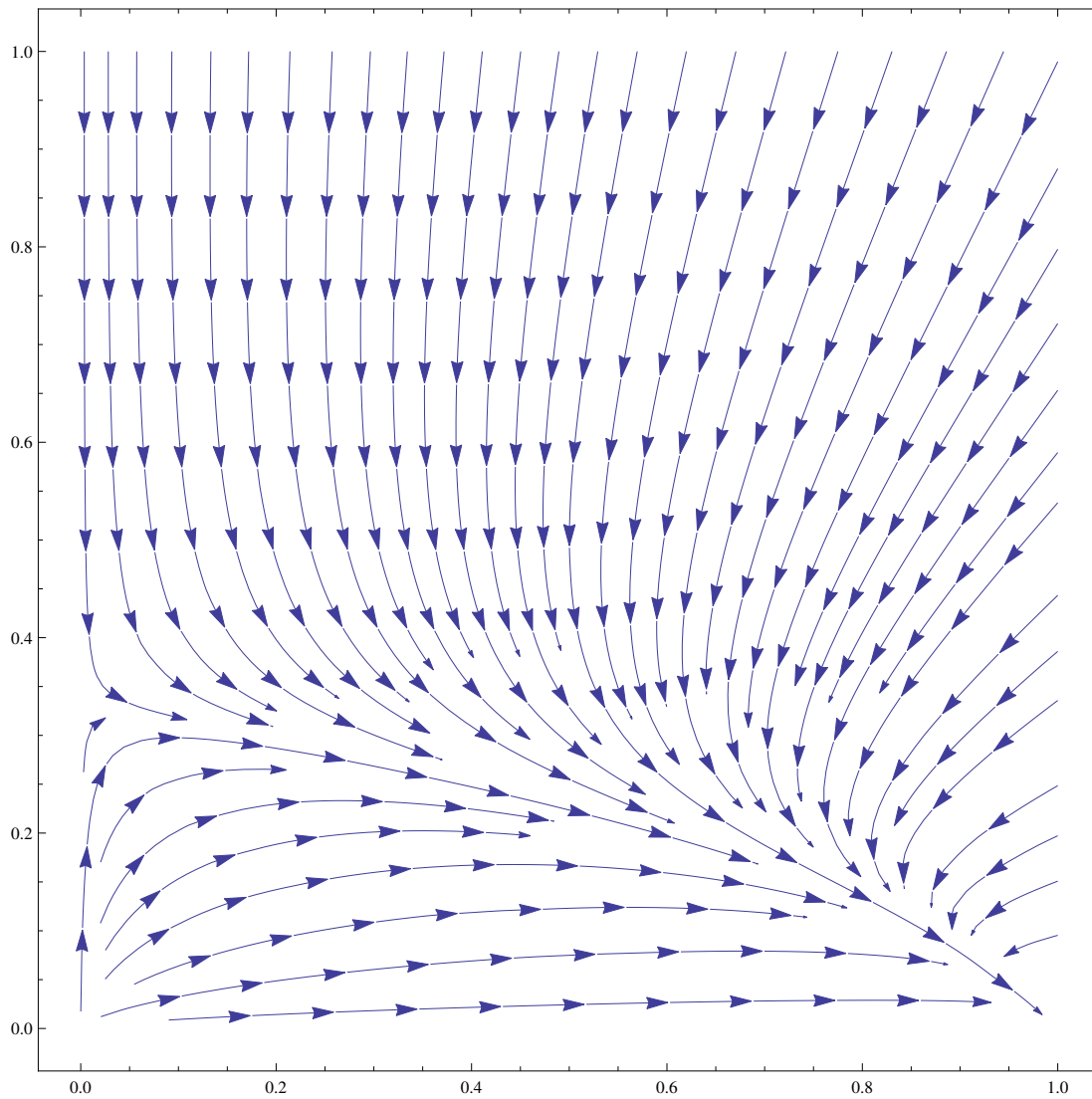


```
Clear[x, y]
Solve[{a - b1 x - b2 y == 0, c - d1 x - d2 y == 0}, {x, y}]
{{x -> 0.307692, y -> 0.384615}}
```

Es gibt einen Limespunkt des Systems, den man direkt ausrechnen kann.

```
(* Bsp2 der Parameter *)
a = 1; b1 = 1; b2 = 1; c = 2/3; d1 = 0.75; d2 = 2;
sys = {f[x, y], g[x, y]}
{x (1 - x - y), (2/3 - 0.75 x - 2 y) y}
```

```
StreamPlot[sys, {x, 0, 1}, {y, 0, 1}]
```



Die y -Spezies stirbt aus, x bleibt uebrig, im Limes wird die Loesung angenommen, die sich aus dem System bei $y = 0$ ergibt :

Solve a logistic equation :

```
restx = DSolve[x'[t] == a x[t] - b1 x[t]^2, x, t]
```

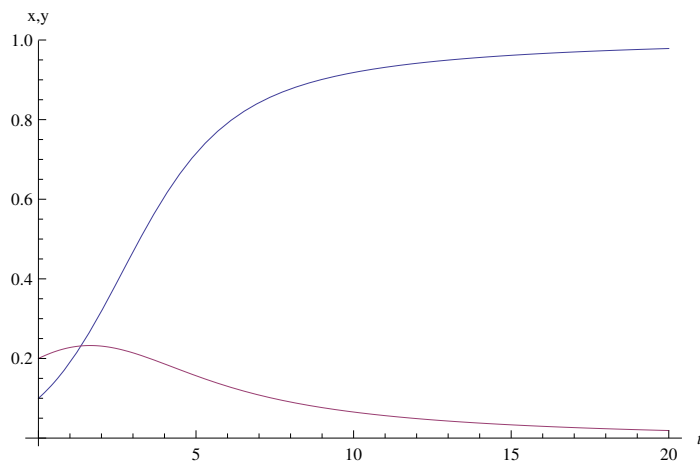
$$\left\{ \left\{ x \rightarrow \text{Function} \left[\{t\}, \frac{e^t}{e^t + e^{c[1]}} \right] \right\} \right\}$$

$$\text{Limit} \left[\frac{e^t}{e^t + e^{c[1]}}, t \rightarrow \text{Infinity} \right]$$

1

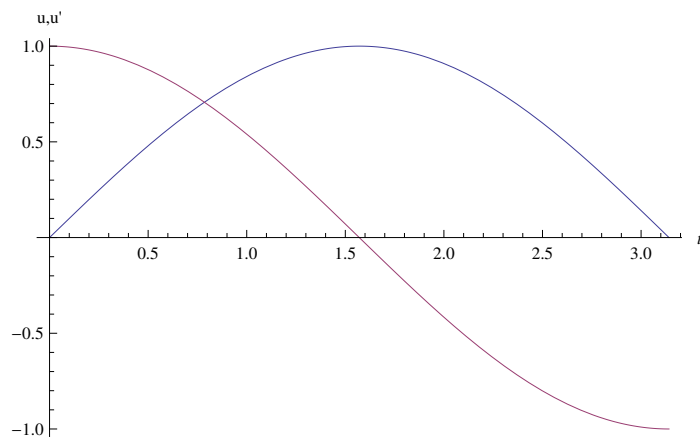
Bsp fuer eine konkrete Kurve mit NDSolve

```
(* Clear[x,y,t,lsg] *)
a = 1.; b1 = 1.; b2 = 1; c = 2./3; d1 = 0.75; d2 = 2;
lsg = NDSolve[{x'[t] == x[t] (a - b1 x[t] - b2 y[t]),
  y'[t] == y[t] (c - d1 x[t] - d2 y[t]), x[0] == 0.1, y[0] == 0.2}, {x, y}, {t, 0, 20}]
{{x -> InterpolatingFunction[{{0., 20.}}, <>],
  y -> InterpolatingFunction[{{0., 20.}}, <>]}}
Plot[{lsg[[1, 1, 2]][t], lsg[[1, 2, 2]][t]}, {t, 0, 20}, AxesLabel -> {t, "x,y"}]
```



```
(* Anderes Bsp, get an InterpolatingFunction object
approximating the solution of a differential equation: *)
ifun = First[
  u /. NDSolve[{u''[t] + u[t] == 0, u[0] == 0, u'[0] == 1}, u, {t, 0, π}]
(* and Plot the function and its derivative: *)
Plot[{ifun[t], ifun'[t]}, {t, 0, π}, AxesLabel -> {t, "u,u'"}]

InterpolatingFunction[{{0., 3.14159}}, <>]
```



```
(* Bsp DGl-System mit Randwerten *)
```

```

dgl = DSolve[{x'[t] == y[t], y'[t] == -x[t], x[0] == 1, y'[1] == 2}, {x[t], y[t]}, t]
{{x[t] -> Cos[t] - Cot[1] Sin[t] - 2 Csc[1] Sin[t],
  y[t] -> -Cos[t] Cot[1] - 2 Cos[t] Csc[1] - Sin[t]}}

```

```

lsg = dgl[[1]] (* Beseitigung der Doppelklammer *)

```

```

{x[t] -> Cos[t] - Cot[1] Sin[t] - 2 Csc[1] Sin[t],
 y[t] -> -Cos[t] Cot[1] - 2 Cos[t] Csc[1] - Sin[t]}

```

```

(* Herausloesung beider Loesungsfunktionen *)

```

```

fx[t_] = x[t] /. lsg

```

```

fy[t_] = y[t] /. lsg

```

```

Cos[t] - Cot[1] Sin[t] - 2 Csc[1] Sin[t]

```

```

-Cos[t] Cot[1] - 2 Cos[t] Csc[1] - Sin[t]

```

```

(* Vereinfachen *)

```

```

fx[t_] = ComplexExpand[fx[t]] // Simplify

```

```

fy[t_] = ComplexExpand[fy[t]] // Simplify

```

```

Csc[1] (Sin[1 - t] - 2 Sin[t])

```

```

-(Cos[1 - t] + 2 Cos[t]) Csc[1]

```

```

f1 = Plot[fx[t], {t, 0, 2 Pi}, AxesLabel -> {t, "fx"}]

```

```

f2 = Plot[fy[t], {t, 0, 2 Pi}, AxesLabel -> {t, "fy"}]

```

```

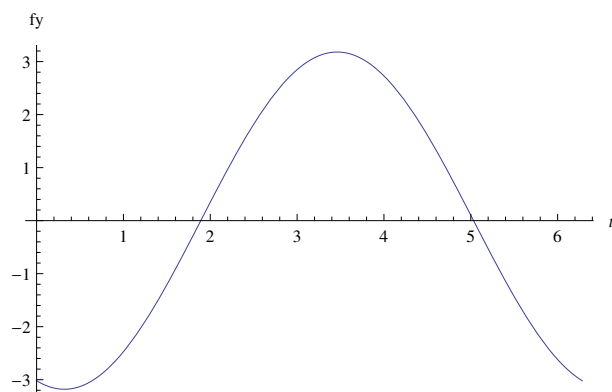
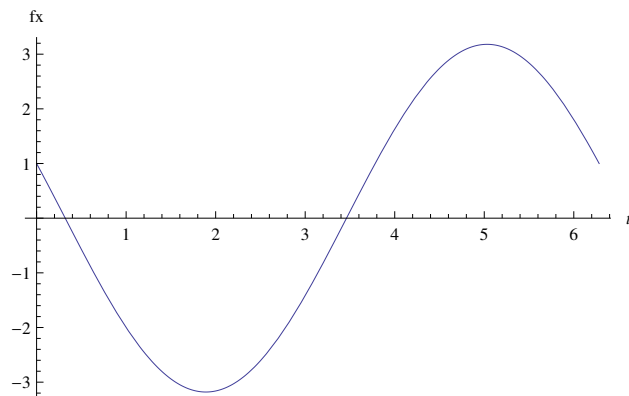
Show[f1, f2]

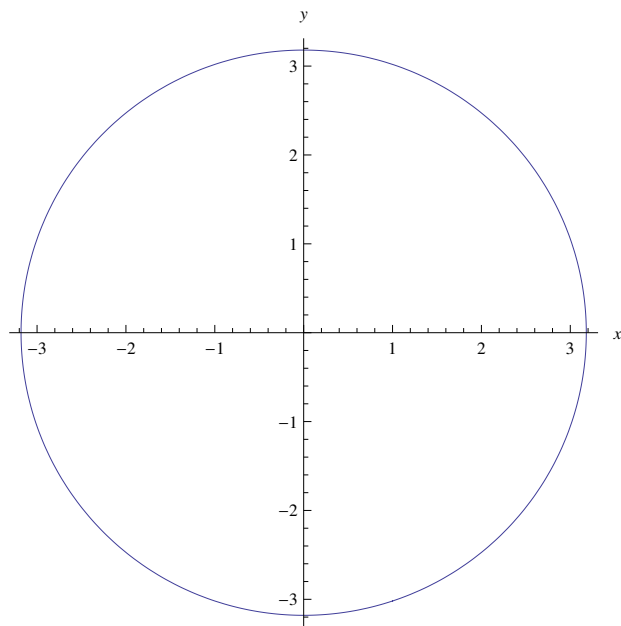
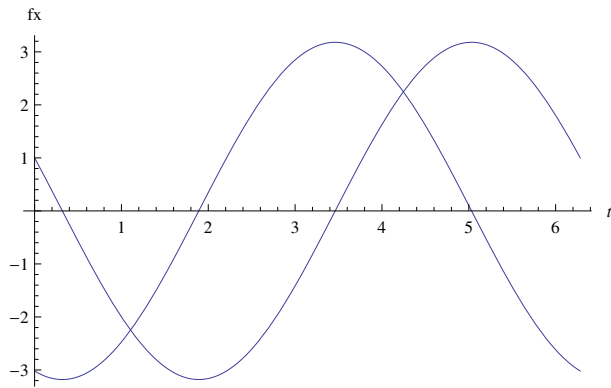
```

```

ParametricPlot[{fx[t], fy[t]}, {t, 0, 2 Pi}, AspectRatio -> 1, AxesLabel -> {x, y}]

```





(* BSP: Michaelis-Menten DGl fuer enzymatische Reaktionen *)

```
mm = DSolve[{x'[t] == -V x[t] / (x[t] + Km), x[0] == 1}, x, t]
```

Solve::ifun : Inverse functions are being used by Solve, so some solutions may not be found; use Reduce for complete solution information. >>

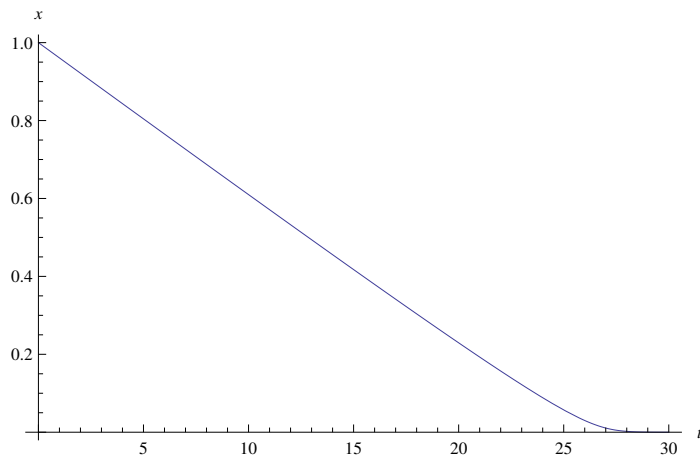
```
{ {x -> Function[{t}, Km ProductLog[ $\frac{1}{Km} - \frac{t V}{Km}$ ]] } }
```

```
xsp[t] = x[t] /. mm /. V -> 0.04 /. Km -> 0.02
```

```
{0.02 ProductLog[50. e50. -2. t] }
```



```
Plot[0.02 ProductLog[50. e50-2 t], {t, 0, 30}, AxesLabel -> {t, x}]
```



Hinweis : ProductLog ist die Loesung der Gleichung for w in $z \downarrow we^w$

```
Plot[ProductLog[x], {x, -1/E, 1}]
```

