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## Lecture 18. Eigenvalues and Eigenvectors.

### 1. Definitions.

In this lecture we are going to answer the question:

Does there exist a basis such that an operator  $T: V \rightarrow V$  has a diagonal matrix in this basis?

Let  $V$  be a finite-dimensional vector space over  $\mathbb{F}$ .

Def. 8.1 A linear operator  $T: V \rightarrow V$  is called diagonalizable if there exists a basis  $v_1, \dots, v_n$  in  $V$  such that

$$M_T = \begin{pmatrix} \lambda_1 & 0 & \dots & 0 \\ 0 & \lambda_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \lambda_n \end{pmatrix} \quad (8.1)$$

in the basis  $v_1, \dots, v_n$

Remark 8.1 If  $M_T$  has a form (8.1), then

$$Tv_i = \lambda_i v_i \quad \text{for all } i=1, \dots, n.$$

Def. 8.2 • A number  $\lambda \in \mathbb{F}$  is called an eigenvalue of  $T$  if there exists  $v \neq 0$  from  $V$  such that  $Tv = \lambda v$

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- The vector  $v$  is called an eigenvector of  $T$  corresponding to the eigenvalue  $\lambda$ .

Ex 8.1 a)  $0v = 0 \quad \forall v \in V$ . (zero map)

Then  $\lambda = 0$  is an eigenvalue of  $0$

- any vector  $v \neq 0 \in V$  is an eigenvector of  $0$  corr. to  $\lambda = 0$ .

• b)  $Iv = v \quad \forall v \in V$  (identity map)

- $\lambda = 1$  - an eigenvalue of  $I$

- any vector  $v \neq 0 \in V$  is an eigenvector of  $I$  corr. to  $\lambda = 1$ .

c)  $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3, \quad T(x, y, z) = (x, y, 0)$

- $\lambda = 1, \quad v = (1, 0, 0), \quad v = (0, 1, 0)$   
 $\uparrow$  eigenvalue  $\quad \nwarrow$  eigenvectors
- $\lambda = 0, \quad v = (0, 0, 1)$

Def 8.3 The set of all eigenvalues of a linear operator  $T: V \rightarrow V$  is called the spectrum of  $T$ . Notation:  $\text{Spec } T$

Def 8.4 Let  $T: V \rightarrow V$  be a linear map and  $\lambda$  be an eigenvalue of  $T$

$$V_\lambda = \{ v \in V : Tv = \lambda v \} = \text{Ker}(T - \lambda I)$$

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is called an eigenspace of  $T$ .

We remark that  $\lambda$  is an eigenvalue of  $T$  if  $\ker(T - \lambda I)$  contains non-zero vectors, that is,  $T - \lambda I$  is not injective.

The following conditions are equivalent:

- $T - \lambda I$  is not injective ( $\dim \ker(T - \lambda I) > 0$ )
- $T - \lambda I$  is not invertible

- $T - \lambda I$  is not surjective ( $\text{rank}(T - \lambda I) < n$ )

## 2. Characteristic polynomial.

Let

$$A = M_T = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ - & - & - & - \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{pmatrix}$$

be a matrix of  $T$  in some basis  $v_1, \dots, v_n$ .

Def 8.5 • The matrix

$$\begin{pmatrix} a_{11} - \lambda & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} - \lambda & \dots & a_{2n} \\ - & - & - & - \\ a_{n1} & a_{n2} & \dots & a_{nn} - \lambda \end{pmatrix} = A - \lambda I$$

is called the characteristic matrix of  $A$

- $\det(A - \lambda I)$  is called the characteristic polynomial of matrix  $A$ .

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Th 8.1 A number  $\lambda$  is an eigenvalue of  $T$  iff it is a root of the characteristic polynomial of matrix  $M_T$  (shortly  $\lambda \in \text{spec } T \Leftrightarrow \det(M_T - \lambda I) = 0$ .)

Proof.  $\lambda \in \text{spec } T \Leftrightarrow T - \lambda I$  is not injective  $\Leftrightarrow$   
 $\Leftrightarrow T - \lambda I$  is not surjective  $\Leftrightarrow$   
 $\Leftrightarrow \text{rank}(T - \lambda I) < n \Leftrightarrow \det(M_T - \lambda I) = 0$ . □

Ex 8.2  $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$

$$T(x, y) = (-y, x)$$

let write  $M_T$  in the standard basis

$$e_1 = (1, 0), e_2 = (0, 1)$$

$$Te_1 = (0, 1), Te_2 = (-1, 0)$$

$$M_T = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$$

To find  $\text{spec } T$ , we compute

$$\det \begin{pmatrix} 0-\lambda & -1 \\ 1 & 0-\lambda \end{pmatrix} = \begin{vmatrix} -\lambda & -1 \\ 1 & -\lambda \end{vmatrix} = \lambda^2 + 1 = 0$$

Since the equation  $\lambda^2 + 1$  has no solutions in  $\mathbb{R}$ ,  $T$  has no eigenvalues.

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Th 8.2 Let  $M_T^e$  and  $M_T^{e'}$  be matrices of a linear operator  $T$  in basis  $e_1, \dots, e_n$  and  $e'_1, \dots, e'_n$ , respectively. Then

$$\det(M_T^e - \lambda I) = \det(M_T^{e'} - \lambda I).$$

In other words, the characteristic polynomial of the matrix of  $T$  does not depend on choice of basis.

Proof. Let  $Q = Q_{ee'}$  be a change-of-basis matrix from  $e$  to  $e'$ . Then, by (7.5)

$$M_T^{e'} = Q^{-1} M_T^e Q$$

$$\text{So, } M_T^{e'} - \lambda I = Q^{-1} M_T^e Q - \lambda I =$$

$$= Q^{-1} M_T^e Q - Q^{-1} \lambda I Q =$$

$$= Q^{-1} (M_T^e - \lambda I) Q. \quad = \frac{1}{\det Q}$$

$$\text{Thus, } \det(M_T^{e'} - \lambda I) = \det Q^{-1} \cdot \det(M_T^e - \lambda I) \cdot \det Q =$$

$$= \det(M_T^e - \lambda I).$$

Corollary 8.1 The characteristic polynomials of similar matrices coincide.

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Th 8.3 Let  $\lambda_1, \dots, \lambda_m$  be distinct eigenvalues of  $T$  with corresponding eigenvectors  $v_1, \dots, v_m$ . Then  $v_1, \dots, v_m$  are linearly independent.

Proof. We assume that  $v_1, \dots, v_m$  are linearly dependent. Then there exists  $k=2, \dots, m$  such that  $v_1, \dots, v_{k-1}$  are linearly independent and

$$v_k \in \text{span} \{v_1, \dots, v_{k-1}\}.$$

This means that  $\exists a_1, \dots, a_{k-1} \in \mathbb{F}$  such that

$$v_k = a_1 v_1 + \dots + a_{k-1} v_{k-1} \quad (8.2)$$

Applying  $T$  to both sides, we have

$$\lambda_k v_k = a_1 \lambda_1 v_1 + \dots + a_{k-1} \lambda_{k-1} v_{k-1} \quad (8.3)$$

subtracting  $\lambda_k$  times (8.2), we have

$$a_1 \underbrace{(\lambda_1 - \lambda_k)}_{\neq 0} v_1 + \dots + a_{k-1} \underbrace{(\lambda_{k-1} - \lambda_k)}_{\neq 0} v_{k-1} = 0$$

$\Rightarrow v_1, \dots, v_{k-1}$  - linearly dependent.

This contradicts the choice of  $k$ .



### 3. Diagonalization

Th 8.4 A linear map  $T: V \rightarrow V$  is diagonalizable iff there exists a basis  $v_1, \dots, v_n$  of  $V$  consisting of eigenvectors of  $T$ . Moreover, if  $T$  is diagonalizable,

⑦ and  $M_T$  is the matrix of  $T$  in basis  $v_1, \dots, v_n$ , then

$$M_T = \begin{pmatrix} \lambda_1 & 0 & \dots & 0 \\ 0 & \lambda_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \lambda_n \end{pmatrix},$$

where  $\lambda_i$  is the eigenvalue corresponding to  $v_i$   $\forall i = 1, \dots, n$ .

Ex 8.3  $A = \begin{pmatrix} 1 & 3 \\ 4 & 2 \end{pmatrix}$ ,  $v_1 = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$ ,  $v_2 = \begin{pmatrix} 3 \\ 4 \end{pmatrix}$   
(A map  $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$  is identified with  $A$ )

$$Av_1 = \begin{pmatrix} 1 & 3 \\ 4 & 2 \end{pmatrix} \begin{pmatrix} 1 \\ -1 \end{pmatrix} = \begin{pmatrix} -2 \\ 2 \end{pmatrix} = -2 \begin{pmatrix} 1 \\ -1 \end{pmatrix} = -2v_1$$

$$Av_2 = \begin{pmatrix} 1 & 3 \\ 4 & 2 \end{pmatrix} \begin{pmatrix} 3 \\ 4 \end{pmatrix} = 5v_2.$$

So,  $v_1, v_2$  are eigenvectors which corr. to

$\lambda_1 = -2$ ,  $\lambda_2 = 5$ . By Th 8.3,  $v_1, v_2$  are independent. So, they form a basis.

By Th. 8.4,

$$M_A = \begin{pmatrix} -2 & 0 \\ 0 & 5 \end{pmatrix}$$

in basis  $v_1, v_2$ .